

1 METHOD AND APPARATUS FOR FILLING VIAS

2 FIELD OF THE INVENTION

3 This invention is directed to a process and apparatus,  
4 and in particular tooling, for enabling the creation of  
5 filled, and preferably conductive, vias and  
6 through-vias in a semiconductor substrate. More  
7 particularly, it is directed to a process and apparatus  
8 for enabling the filling of such vias.

9 BACKGROUND OF THE INVENTION

10 There are many advantages to using silicon as a  
11 substrate for electronic packaging, rather than  
12 traditional ceramic and organic laminate packaging.  
13 Some of the key features of the silicon carrier  
14 include: the ability to create high performance wiring  
15 and joining at much finer pitch than typical packaging,  
16 the ability to join heterogeneous technologies or  
17 different generation technologies for high speed  
18 applications, the ability to integrate passives, MEMs  
19 or optical fibers, the ability to add silicon  
20 functionality to the carrier package in addition to  
21 wiring, the ability to dramatically increase the I/O  
22 density, and for many applications, the ability to  
23 reduce overall system cost when compared to other  
24 system on package (SOP) approaches which do not use Si  
25 as the carrier.

1 Elements and structures of semiconductor packages have  
2 been described in United States Patent No. 5,998,292 to  
3 Black et al. and United States Patent No. 6,593,644 to  
4 Chiu et al. In order to attain the advantages outlined  
5 above several key steps are necessary, as shown in  
6 Figs. 1A to 1F. As illustrated in Fig. 1A, first,  
7 deep blind vias 10 (several hundred microns in depth) are  
8 etched into a silicon wafer 12, and sidewall insulation  
9 14 is deposited. As shown in Fig. 1B, vias 10 must be  
10 completely filled with a conductor 16. Once the vias  
11 are filled, as shown in Fig. 1C, standard BEOL wiring  
12 levels 18 can be built on top of the silicon wafer 12,  
13 and the whole wafer can be thinned by backside grinding  
14 to expose the via conductors on the backside, as shown  
15 in Fig. 1D. As shown in Fig. 1E, solder connections,  
16 such as C4 solder balls 20 may then be built on the  
17 carrier back, and chips 22 may be joined to the front,  
18 by any one of a number of conventional techniques such  
19 as flip chip bonding as illustrated in Fig. 1F,  
20 completing the high performance silicon carrier package  
21 24.

22 At this point there are several options, one of which  
23 is illustrated in Fig. 2, where the high performance  
24 silicon carrier package 24 is joined to a ceramic  
25 module 26 by means of solder balls 20, and then to a PC  
26 board 28 by means of, for example, additional C4 solder  
27 balls 30.

1 Of all the key technology elements described above,  
2 that which is most problematic is the filling of high  
3 aspect ratio blind vias with conductor. Filling with  
4 common metals by PVD or CVD methods is impractical,  
5 while plating becomes extremely difficult due to the  
6 tendency for the plated side walls to "breadloaf" at  
7 the top, cutting off the via from further filling, and  
8 trapping plating solution in a central void. Even if  
9 these or other methods of solid metal filling, such as  
10 filling with molten metal, could be made to work,  
11 typical metals have a large coefficient of thermal  
12 expansion (CTE) mismatch with silicon. There are three  
13 potential problems associated with large CTE mismatches  
14 between the vias and the silicon substrate:  
15 delamination at the via side walls; cracking of the  
16 silicon substrate between vias; and piston-like rupture  
17 of any overlying or underlying structures or thin films  
18 in contact with the top/bottom surfaces of the vias.  
19 Accordingly it is advantageous to use a material which  
20 is simultaneously conductive with a good CTE match to  
21 silicon.

22 One such material which has been used by International  
23 Business Machines Corporation in the production of  
24 glass ceramic multi-chip modules (MCM) is a paste  
25 containing a mixture of copper and glass particles  
26 suspended in a mixture of organic solvents and binders.  
27 Such pastes are typically applied to a patterned  
28 ceramic greensheet by a screen printing method, after  
29 which the sheets are stacked and sintered at high

1 temperature, during which the organic components are  
2 burned off, and the glass and Cu components coalesce to  
3 form conductive lines and vias.

4 Recently, in "Filling the Via Hole of IC by VPES  
5 (Vacuum Printing Encapsulation Systems) for stacked  
6 chip (3D packaging)", Atsushi Okuno and Noriko Fujita,  
7 2002 Electronic Components and Technology Conference  
8 have described the adaptation of a vacuum printing  
9 encapsulation system (VPES) for filling blind vias with  
10 conductive paste. The VPES method was originally used  
11 to deliver plastic resin in the manufacture of ball  
12 grid array (BGA) and CSP packaging, wafer level CSP  
13 packaging, transparent resin encapsulating for light  
14 emitting diode (LED) displays, flip-chip under-filling,  
15 and other processes. For BGA or CSP packaging,  
16 following die bonding and wire bonding on a printed  
17 circuit board substrate, the printing of liquid resin  
18 takes place using a squeegee applied to the substrate  
19 under vacuum. The substrate is then cured at a high  
20 temperature to solidify the liquid resin. After curing,  
21 solder balls for terminals are mounted on the backside  
22 of the substrate. Conventional screen printing lacked a  
23 process for removing the gas from the resin after the  
24 printed after curing, causing cracking or warping  
25 during the high temperature process.

26 In the method described by Okuno, a squeegee tool  
27 applies conductive paste using a knife edge. In this  
28 tool design, a vacuum is pulled inside the enclosure,

1 and paste is delivered, for illustrative example, by a  
2 slot in the base of the tool.

3 An example of via filling using such a tool is shown in  
4 Figs. 3A through Fig. 3F. In these figures, a vacuum  
5 chamber 34 is evacuated by means of a vacuum pump (not  
6 shown) connected to chamber 34 by a vacuum hose 36.  
7 Once sufficient vacuum is created, a squeegee blade 38,  
8 mounted on a moving member 39, moves across the surface  
9 of a via containing wafer 40 from left to right in the  
10 figure, held in a wafer holder or base plate 42,  
11 delivering paste 44 at its leading edge. Paste 44 is  
12 moved into position by a moving support 46 in a channel  
13 or base plate slot 48 to which paste 44 is conducted by  
14 a passageway (not shown). As shown in Fig. 3C, excess  
15 paste is deposited over a movable support member 50 in  
16 a channel or base plate slot 52. As shown in Fig. 3D,  
17 support member 52 is moved upwards in channel 52, while  
18 support member 46 is moved downwards in channel 48.  
19 Additional paste is supplied to slot 52 through a  
20 second passageway (not shown). As illustrated in Fig 3E  
21 and Fig 3F, moving member 39 is then moved to cause  
22 squeegee blade 38 to again traverse wafer 40, while  
23 moving from right to left in the figure.

24 This method has a number of important shortcomings, the  
25 most important of which is that there is not sufficient  
26 constraint at the leading edge of the squeegee blade 38  
27 to force the paste 44 to the bottom of a deep blind via  
28 in a single, or often, even multiple passes. Whether

1 the paste 44 makes it to the via bottom is dependent on  
2 a number of factors including the viscosity of the  
3 paste 44 , the down force on the squeegee blade 38, the  
4 quantity of paste 44 built up in front of the squeegee  
5 blade 38, and the blade speed. With respect to the  
6 down force, there is no method to fully contain the  
7 paste 44 under pressure over a blind via except when  
8 the squeegee blade 38 is passing directly overhead, and  
9 even then paste 44 is free to smear out both in front  
10 of and behind the blade 38. This makes multiple passes  
11 a necessity. For high aspect ratio vias incomplete  
12 filling can occur if the vacuum level is not  
13 sufficiently low or if the paste 44 is of a very high  
14 viscosity. The method is also not well suited to  
15 semiconductor processing where substrates are round  
16 rather than rectangular. In order to ensure complete  
17 coverage of a round substrate, paste 44 must be pushed  
18 repeatedly onto and off of the base plate 42 holding  
19 the wafer. The linear motion of the squeegee blade 38  
20 then leads to buildup at either end of the tool  
21 necessitating some method of regular cleaning, and a  
22 great waste of the conductive fill paste. Accordingly  
23 there is a need to develop a more efficient method for  
24 applying viscous conductive paste to semiconductor  
25 wafers containing blind vias.

26 In United States Patent No. 5,244,143 to Ference et al.  
27 as well as United States Patent No. 5,775,569 to Berger  
28 et al., a tool and method for filling a mold with  
29 molten solder are described. Since a mold is obviously

1 a rigid plate containing etched regions of specific  
2 shapes, if these shapes take the form of cylinders then  
3 the problem is essentially one of filling blind vias.  
4 The filling head described in these patents is sealed  
5 against the mold surface such that a vacuum can be  
6 pulled in a region defined by a O-ring seal underneath  
7 the head. Molten solder is then delivered through a  
8 central slot in the head such that complete fill of the  
9 evacuated solder mold cavities is achieved in a single  
10 pass. An important distinguishing feature of this tool  
11 and method is that it works well only for very low  
12 viscosity materials such as molten solder which have a  
13 viscosity on the order of 2 centipoise (for comparison  
14 water is by definition 1 centipoise). The conductive  
15 pastes used for semiconductor applications by contrast  
16 have much higher viscosities ranging from 1,000  
17 centipoise to greater than 50,000 centipoise and thus  
18 require much higher internal pressures for them to be  
19 effectively delivered to the wafer surface and into the  
20 blind vias etched therein.

21 A via filling method using a pressurized paste nozzle  
22 is described in United States Patent No. 6,506,332 to  
23 J. L. Pedigo and it is clear that while this method has  
24 advantages over the squeegee method described by Okuno,  
25 it is primarily intended for use in organic printed  
26 circuit board (PCB) high-density interconnect (HDI) and  
27 sequential build up (SBU) laminate board type  
28 applications. The apparatus described makes use of a  
29 pressure head in combination comprising an O-ring

1 gasket which is held against the electronic substrate  
2 to be filled and moved relative to that substrate such  
3 that paste is forced into the via holes as the head  
4 passes overhead. The apparatus as described has a  
5 number of shortcomings which limit its applicability  
6 for use with silicon wafer based packaging.  
7 Specifically, the method does not employ vacuum which  
8 is a practical necessity for complete filling of small,  
9 high aspect ratio blind vias. Instead, the method is  
10 described as a means of obtaining "reduced numbers of  
11 air pockets formed in the via fill paste while  
12 decreasing the amount of processing required per  
13 board". Further, via sizes claimed range from 2 to 25  
14 thousands of an inch (mils) in diameter, a span which  
15 covers most important electronic wiring board  
16 applications, but which neglects via features smaller  
17 than 50 um (2 mils) in diameter which are easily  
18 attainable in package substrates made from silicon  
19 where blind vias may be on the order of 10 um in  
20 diameter with aspect ratios greater than 10:1. Filling  
21 such small blind features with viscous paste without  
22 the aid of vacuum is highly problematic if not  
23 impossible.

#### 24 SUMMARY OF THE INVENTION

25 The present inventors have recognized that there is a  
26 need for a method and tooling which employs a  
27 combination of pressurized paste delivery in a vacuum  
28 environment to enable the complete filling of etched



1 blind features, both lines and vias, in a silicon wafer  
2 which may range in size from 10 um (< 0.5 mils) to 250  
3 um (10 mils). Furthermore, there is a need for a  
4 highly manufacturable process and tooling which is  
5 easily adaptable for highly automated batch operation  
6 compatible with CMOS back end of the line (BEOL)  
7 processing.

8 It is therefore an aspect of the present invention to  
9 provide a method for reliably filling vias with a  
10 viscous substance.

11 It is another aspect of the present invention to  
12 provide apparatus or tooling for reliably filling vias  
13 with a viscous substance.

14 In accordance with the invention a method for filling  
15 vias, and in particular blind vias, in a wafer,  
16 comprises evacuating air from the vias; trapping at  
17 least a portion of the wafer and a paste for filling  
18 the vias between two surfaces; and pressurizing the  
19 paste to fill the via. The method may further comprise  
20 forming a seal between the surfaces so as to enclose  
21 the portion of the wafer and the paste. The method may  
22 further comprises moving the seal over successive  
23 portions of the wafer to fill the vias.

24 Further, the method may comprise placing the paste on a  
25 planar surface facing the wafer; and moving the planar  
26 surface upon which the paste is placed into contact

1 with the wafer. The paste may be injected between one  
2 of the surfaces and the wafer. Preferably, the paste  
3 is injected between one of the surfaces and the wafer  
4 after evacuating the air from the vias.

5 The method may further comprising providing an  
6 evacuated space between the surfaces; and forcing the  
7 surfaces together to force the paste into the vias. The  
8 surfaces can forced together by atmospheric pressure.

9 Preferably, the paste is pressurized to greater than  
10 atmospheric pressure, and more specifically to a  
11 pressure in the range of 10 to 100 PSI.

12 In accordance with the invention, an apparatus for  
13 filing vias in a wafer, comprises a chamber in which to  
14 place the wafer, the chamber being capable of being  
15 evacuated; a surface upon which to place the wafer; a  
16 paste delivery portion for providing a paste to fill  
17 the vias; and a paste filling portion for bringing the  
18 paste into contact with the vias under pressure so that  
19 the paste fills the vias. Preferably, the paste  
20 filling portion provides the paste at a pressure with  
21 the range of 10 to 100 PSI.

22 The paste delivery portion may comprise a surface onto  
23 which the paste is deposited; and a mechanism for  
24 applying pressure so that the paste on the surface is  
25 forced into contact with the wafer. The paste delivery  
26 portion may also comprise a surface onto which the

1 paste is deposited; and a passageway through which the  
2 paste is delivered to the surface. The mechanism for  
3 applying pressure may comprise a plate which defines  
4 the surface; and components for applying a pressure  
5 differential to the plate so as to force the plate  
6 toward the wafer. A compliant material may be disposed  
7 on the surface to which the paste is applied.

8 The paste filling portion may comprise a plate having a  
9 portion for receiving the paste; a first seal for  
10 sealing the plate to the surface upon which the wafer  
11 is placed; a second seal for sealing the paste between  
12 the plate and the plate and the wafer; and a mechanism  
13 for forcing the plate towards the wafer so that the  
14 paste is forced into the vias of the wafer.

15 The mechanism for forcing the plate towards the wafer  
16 may comprise a gas removal apparatus for evacuating gas  
17 between the plate and the surface upon which the wafer  
18 is placed; and gas replacement apparatus for replacing  
19 gas evacuated from the chamber. The gas replacement  
20 apparatus may comprise an opening through which gas is  
21 permitted to enter the chamber.

22 The surface upon which to place the wafer may comprise  
23 a base plate having a recess for the wafer or it may be  
24 a surface of an electrostatic chuck.

25 The paste delivery portion may comprise a pressurized  
26 paste reservoir.

1 Also in accordance with the invention, the paste  
2 filling portion may comprise a piston housing having an  
3 opening for receiving a piston; a compliant seal for  
4 sealing the piston housing to a portion of the wafer so  
5 as to confine the paste; a piston disposed in the  
6 piston housing; and a piston actuator for forcing the  
7 piston toward the wafer; wherein the paste delivery  
8 portion provides the paste to the opening.

9 The apparatus in accordance with the invention may  
10 further comprise a mechanism for moving the piston  
11 housing so that the seal is compressed for filing the  
12 vias. The mechanism for moving the piston housing may  
13 further move the piston housing to a position wherein  
14 the seal is compressed to a lesser degree than when the  
15 vias are filled, to thereby allow the piston housing to  
16 be moved so that the piston housing is disposed so as  
17 to be in a position to fill vias of one or more  
18 successive portions of the wafer with paste delivered  
19 to the opening.

20 The apparatus may further comprise a mechanism for  
21 cleaning the piston of excess paste after vias of a  
22 wafer have been filled.

23 The paste filling portion of the apparatus may comprise  
24 an elongate member having a surface with a slot through  
25 which paste is provided to the wafer; and a compliant  
26 seal for sealing the surface to the wafer.

1 In accordance with the invention, the apparatus may  
2 further comprise a mechanism for translating the member  
3 and the wafer with respect to one another so as to fill  
4 vias in successive portions of the wafer and a  
5 mechanism for rotating the member and the wafer with  
6 respect to one another so as to fill vias in successive  
7 portions of the wafer. The mechanism for rotating the  
8 member and the wafer with respect to one another may  
9 comprise a rotating base having the surface upon which  
10 the wafer is placed.

11 The apparatus may be configured to accept a circular  
12 wafer, wherein the elongate member is disposed radially  
13 with respect to the wafer. Preferably, the elongate  
14 member has a length less than that a radius of the  
15 wafer, and the further comprises a mechanism for  
16 rotating the wafer; and a mechanism for radially  
17 translating the member in a radial direction with  
18 respect to the wafer. The mechanism for rotating the  
19 wafer may include a rotation speed control to control  
20 speed of rotation of the wafer. The mechanism for  
21 radially translating the member may include a  
22 translation speed control to control speed of  
23 translation of the member with respect to the wafer.

24 The mechanism for radially translating the member may  
25 include a worm gear assembly, and a motor for rotating  
26 a drive shaft of the assembly.

1     BRIEF DESCRIPTION OF THE DRAWINGS

2     These and other aspects, features, and advantages of  
3     the present invention will become apparent upon further  
4     consideration of the following detailed description of  
5     the invention when read in conjunction with the drawing  
6     figures, in which:

7     Fig. 1A to Fig. 1F illustrate, in cross sections, the  
8     stages of a prior art process flow for creating a  
9     silicon-based chip carrier complete with conductive  
10    through vias, topside landing joins or bumps and  
11    backside solder connections.

12    Fig. 2 illustrates prior art silicon based carrier  
13    populated with chips mounted on a first (ceramic  
14    module) and second (PCB) level package.

15    Fig. 3A illustrates a prior art system using paste  
16    delivery through a base plate slot with a vacuum  
17    squeegee blade at a home position.

18    Fig. 3B illustrates the system of Fig. 3A with the  
19    vacuum squeegee blade at a midway position during a  
20    first pass paste filling.

21    Fig. 3C illustrates the system of Fig. 3A with the  
22    vacuum squeegee blade at a terminal position after a  
23    single pass.

1 Fig. 3D illustrates the system of Fig. 3A with paste  
2 delivery through a base plate slot with the vacuum  
3 squeegee blade at terminal position.

4 Fig. 3E illustrates the system of Fig. 3A with the  
5 vacuum squeegee blade at a midway position during a  
6 second (return) pass paste filling.

7 Fig. 3F illustrates the system of Fig. 3A with the  
8 vacuum squeegee blade at a home position after one  
9 complete cycle including two passes across the surface  
10 of a wafer.

11 Fig. 4A illustrates an apparatus in accordance with the  
12 invention with a vacuum piston tool having an upper  
13 surface coated with paste, in an initial position.

14 Fig. 4B illustrates the apparatus of Fig. 4A in a  
15 configuration wherein an inner vacuum port of the is  
16 held open while an outer vacuum port back fills to  
17 atmosphere.

18 Fig. 4C illustrates the apparatus of Fig. 4A in a  
19 configuration wherein the inner port is set to back  
20 fill to atmosphere so that a paste is in the vias of  
21 the wafer and an overburden is on the wafer surface.

22 Fig. 5A is a cross-sectional view of an apparatus in  
23 accordance with a second embodiment of the invention

1 wherein a compact piston head is in a starting position  
2 on the surface of a wafer.

3 Fig. 5B is a cross-sectional view of the apparatus of  
4 Fig. 5A wherein the compact piston head is moved so as  
5 to compress a gasket against the wafer.

6 Fig. 5C is a cross-sectional view of the apparatus of  
7 Fig. 5A wherein paste is dispensed into an evacuated  
8 region between the piston face and the wafer surface.

9 Fig. 5D is a cross-sectional view of the apparatus of  
10 Fig. 5A wherein the piston extends downward compressing  
11 paste into blind vias of the wafer.

12 Fig. 5E is a cross-sectional view of the apparatus of  
13 Fig. 5A wherein the piston is withdrawn and the piston  
14 head is in a position resulting in light pressure  
15 between the gasket and the surface of the wafer.

16 Fig. 5F is a cross-sectional view of the apparatus of  
17 Fig. 5A wherein the piston head is in a second  
18 location, while maintaining a light contact force  
19 between the gasket and the surface of the wafer.

20 Fig. 5G is a side elevational view of the piston head  
21 apparatus of Fig. 5A wherein the piston is at location  
22 away from the wafer surface and extends to contact  
23 apparatus for removing excess paste.



1 Fig. 6A is a partial bottom view of an apparatus in  
2 accordance with a third embodiment of the invention.

3 Fig. 6B cross-sectional side elevational view of the  
4 apparatus of Fig. 6A.

5 Fig. 7 is a cross-sectional view a vacuum paste nozzle  
6 dispense chamber, utilizing the apparatus of Fig. 6A  
7 and Fig. 6B.

8 Fig. 8 is a plan view of a linear nozzle dispense  
9 operation inside of a vacuum environment, utilizing the  
10 apparatus of Fig. 6A and Fig. 6B.

11 Fig. 9A, Fig. 9B and Fig. 9C are plan views of rotary  
12 nozzle dispense operations inside of a vacuum  
13 environment, utilizing an apparatus in accordance with  
14 Fig. 6A and Fig. 6B.

15 DESCRIPTION OF THE INVENTION

16 Variations described for the present invention can  
17 be realized in any combination desirable for each  
18 particular application. Thus particular limitations,  
19 and/or embodiment enhancements described herein, which  
20 may have particular advantages to the particular  
21 application need not be used for all applications.  
22 Also, it should be realized that not all limitations  
23 need be implemented in methods, systems and/or

1 apparatus including one or more concepts of the present  
2 invention.

3 Referring to Fig. 4A, in a first apparatus and method  
4 in accordance with the invention, an outer processing  
5 chamber 60 has an outer vacuum port 62 to which a  
6 vacuum source (not shown) is connected. Chamber 60 is  
7 evacuated, as represented by arrow 65, through port 62.  
8 Conductive paste 64 is applied to a portion of one face  
9 of a top plate or piston 66, which is coated with  
10 Teflon or another nonstick and compliant surface  
11 material 68.

12 As used herein, the term paste refers to any material,  
13 and especially to electrically conductive materials,  
14 having a viscosity within a broad range, including a  
15 range spanning that of traditional pastes, such as  
16 highly loaded metal or metal-dielectric filled pastes  
17 used in screen printing of printed circuit boards,  
18 aqueous suspensions containing fine grains of  
19 conducting material, and organo-metallic liquids.

20  
21 An inner O-ring 69 surrounds the surface material and  
22 the paste 64. The wafer 70 being processed is held on  
23 the face of a bottom or base plate 72 by means of a  
24 countersunk recess or banking pins (not shown). The  
25 planar surfaces of piston 66 and base plate 72 are held  
26 apart by a compliant outer O-ring 74. Air in the  
27 gap separating the paste-coated side from the wafer, is  
28 prevented from being trapped in the vias under the

1 paste by achieving a sufficient vacuum in the space 75  
2 between piston 66 and base plate 72. This is  
3 accomplished by evacuating space 75 by means of a  
4 passageway 76 in piston 66, which is connected to a  
5 vacuum hose 78, that is in turn evacuated by a vacuum  
6 system (not shown) connected to an inner vacuum port  
7 80. Thus, in Fig. 4A, the inner vacuum port 80 and the  
8 outer vacuum port 62 are both open so that the space 75  
9 between the paste 64 and the wafer 70 is evacuated  
10 without collapse of the plates toward one another.

11 Pressure is then applied to the piston 66, bringing the  
12 paste into contact with the wafer 70. As shown in Fig.  
13 4B this pressure, represented by arrows 82 is easily  
14 achieved by maintaining vacuum inside the piston  
15 enclosure defining space 75, while back filling the  
16 outer chamber 60 with air, for example, at atmospheric  
17 pressure, as represented by arrow 65A. The inner  
18 O-ring 69 forms a baffle enclosure, preventing the  
19 paste from escaping at the edge of the wafer 70 and  
20 assuring that sufficient pressure is available to force  
21 the paste into the evacuated vias of wafer 70. Once  
22 the vacuum is released from the inner piston, by  
23 releasing the vacuum at inner vacuum port 80, and  
24 allowing space 75 to revert to, for example,  
25 atmospheric pressure, with arrow 80A representing the  
26 flow of air, outer O-ring 74 provides a restoring force  
27 which increases the separation between piston 66 and  
28 base plate 72, as shown in Fig. 4C.

1 Several additional features are available for the  
2 apparatus illustrated in Fig 4A to Fig. 4C. In the  
3 case of a lower viscosity liquid paste, as shown in  
4 Fig. 4B, delivery may be achieved via an orifice 84 in  
5 the piston 66 and surface material 68 after the vessel  
6 is evacuated. In this case a precise amount of paste  
7 is delivered, through a preferably flexible paste  
8 delivery tube 86 (which may penetrate chamber 60 in an  
9 airtight manner) and allowed to flow across the wafer  
10 surface and into the evacuated vias before final  
11 pressure is applied. In an alternate embodiment, the  
12 wafer mounting surface and paste-covered surface are  
13 inverted. In this case, the automatic dispensing of  
14 the paste takes place through an orifice in the lower  
15 plate, and a lower-viscosity paste is allowed to pool  
16 for a precise time before the wafer is brought into  
17 contact and pressure applied. This may be visualized  
18 by inverting Fig. 4B. In this embodiment, paste  
19 overburden must be removed in a subsequent step by any  
20 number of methods including but not limited to a  
21 squeegee or doctor blade as described above, or a  
22 rotary brush cleaning method.

23 Referring to Fig. 5A to Fig. 5F, in the second  
24 embodiment of the invention, a compact piston 90 is  
25 disposed in a piston housing 91, of a movable, compact,  
26 operating piston head 92. Piston head 92 is disposed  
27 inside a vacuum chamber 94. Provision is made to move  
28 the compact piston head 92 in steps across the surface  
29 of a wafer 96 held in, for example, an electrostatic

1 chuck 98. The filling begins once the chamber 94 is  
2 fully evacuated. As illustrated in Fig. 5B, the piston  
3 head 92 is moved to an appropriate starting point (Fig.  
4 5a) and the piston housing 91 is pushed vertically  
5 against the wafer surface, by for example, vertical  
6 expansion of an actuator 99, to compress an O-ring  
7 gasket 100. As illustrated in Fig. 5C, paste, stored  
8 in a pressurized paste feed and reservoir 102 is  
9 dispensed into the evacuated space 108 underneath the  
10 compact piston through a paste feed tube or hose 104  
11 terminating in an opening 106 in the space 108 under  
12 piston 90 and above wafer 96.

13 As illustrated in Fig. 5D, the piston 90 is then  
14 actuated by a piston drive mechanism 110, which forces  
15 piston 90 downward, thus compressing the paste into the  
16 vias of wafer 96 below. Piston drive mechanism 110 may  
17 be operated in any of several conventional ways, such  
18 as by means of an electric motor or a pneumatic or  
19 hydraulic drive. Drive mechanism 110 may then be  
20 reversed so that piston 90 withdraws. The downward  
21 force of the piston housing 91 of head 92 is released  
22 by actuator 99, so that O-ring gasket 100 decompresses  
23 but remains lightly in contact with the upper surface  
24 of wafer 96. As illustrated in Fig. 5F, the entire  
25 head 92 is translated across the surface of the wafer  
26 96 to the next delivery location and the process  
27 described above is repeated. This may be done at  
28 successive locations until vias in the entire wafer  
29 accessible by the head are filled. This method is

1        advantageous in that it becomes quite easy to deliver  
2        the paste directly to the point of use. Further, as  
3        illustrated in Fig 5G, it is relatively simple to  
4        include a cleaning station, comprising, for example, a  
5        rotating cleaning wheel 112, located away from the  
6        wafer chuck 98, to remove excess paste from the bottom  
7        of the compact piston face before subsequent filling.  
8        To perform this operation, head 92 is moved to a  
9        position removed from chuck 98, and piston drive  
10       mechanism 110 moves piston 90 so that its lower surface  
11       extends outside of piston housing 91 and below O-ring  
12       gasket 100.

13       It is noted that face of piston 90 face may be  
14       circular, it is advantageous for it to be a square or  
15       rectangular in the case of a x-y translation system.  
16       In the case of a rotational system where the head is  
17       fixed and the wafer rotates, it is advantageous for the  
18       head to assume a shape equal to some reasonable segment  
19       of a circle.

20  
21       Referring to Fig. 6A (a partial bottom view), Fig. 6B  
22       (a cross-sectional view) and Fig. 7, a cross sectional  
23       view), in a third embodiment of the invention, paste is  
24       applied using a pressurized nozzle 120, having an  
25       O-ring seal or gasket 121 held firmly in contact with  
26       the upper surface of a wafer 122. Wafer 122 is  
27       supported in a countersunk notch or recess 124 of a  
28       base plate 126 inside a vacuum environment, such as a  
29       vacuum chamber 128. Conductive paste 129 is applied

1 through a slot 131. In Fig. 7, nozzle 120 is shown  
2 moving across wafer 122 in the direction of arrow 130.  
3 As with the first and second embodiment, no filling  
4 occurs until the entire chamber 128 has been pumped  
5 down to a vacuum level of less than 10 Torr, and  
6 preferably closer to 1 Torr. Conductive paste, under  
7 pressure, is supplied to nozzle 120 via a delivery tube  
8 132 connected to a paste reservoir 134, which supplies  
9 paste upon movement of a piston assembly 135. An  
10 advantage of this embodiment is that the pressurized  
11 paste cartridge supplying the paste to the nozzle via  
12 the delivery tube is disposed inside the vacuum chamber  
13 and may be electronically or mechanically actuated  
14 therein. In this configuration there is no possibility  
15 of air seeping into the paste delivery system, and  
16 provision is made for preventing air from slowly  
17 permeating the paste itself, which is of critical  
18 importance for pastes which have been purposefully  
19 mixed and dispensed under vacuum specifically for this  
20 application.

21 Referring also to the linear scanning operation shown  
22 in Fig. 8, the nozzle 120 begins at a position to the  
23 left of the wafer 122 held in countersunk recess 124 of  
24 base plate 126 (Fig. 7), and travels as indicated by  
25 arrow 127. It is preferable that recess 124 either  
26 match, or be slightly less deep than, the full  
27 thickness of wafer 122 to ensure that the upper surface  
28 of wafer 122 is either on grade, or slightly higher (~  
29 1 mil) than, the surface of the base plate over which

1 nozzle 120 moves. This ensures that the compliant  
2 nozzle O-ring gasket 121 will remain in compressed  
3 contact against the upper surface of wafer 122  
4 throughout the filling operation. As described, for a  
5 paste of a given viscosity the controllable filling  
6 parameters are vacuum level inside the chamber 128,  
7 pressure applied to the paste inside the nozzle 120,  
8 and scanning speed of nozzle 120 over the surface of  
9 wafer 122.

10 It is noted that with the exception of the rotary  
11 embodiments shown in Figs. 9A, 9B and 9C, below the  
12 wafer fits snugly into a machined, countersunk notch in  
13 the tool base plate so that the wafer surface is very  
14 nearly planar with respect to the base plate surface.  
15 The nozzle moves across the surface filling the  
16 evacuated vias in its path and leaving only a very thin  
17 overburden on the wafer surface. Alternatively,  
18 positioning or banking pins may be used to hold the  
19 wafer in place.

20 As shown in Figs. 9A and 9B, the pressurized paste  
21 nozzle may also be advantageously applied in a rotary  
22 configuration wherein the wafer is held on a rotating  
23 base plate (not shown in Figs. 9A to 9C) by, for  
24 example an electrostatic chuck (also not shown). The  
25 wafer 122A, 122B, 122C rotates as represented by arrow  
26 125. The electrostatic chuck may be of conventional  
27 design with respect to the manner in which the wafer is  
28 held, but may differ in that provisions are made for



1 applying the voltage used to secure the wafer with  
2 electrical connection means that permit rotation of the  
3 base plate.

4 A nozzle 120A is held stationary in a radial direction  
5 with respect to a rotating wafer 122A to apply paste  
6 123A. This method has the advantage that the nozzle  
7 never touches another surface except that of the wafer  
8 to be filled. The nozzle may be designed to be less  
9 wide than the wafer radius to provide an edge exclusion  
10 zone where no paste is applied. Both of these features  
11 serve to make this embodiment of the invention  
12 particularly compatible with typical CMOS semiconductor  
13 processing.

14 The wafer is fixed on a rotating chuck (for example, an  
15 electrostatic chuck, as described above) and the paste  
16 nozzle is brought into contact with the wafer and moves  
17 across the surface filling the evacuated vias in its  
18 path and leaving a very thin overburden of the paste  
19 123A on the surface of wafer 122A. As shown in Fig.  
20 9A, a fixed nozzle can have a slot dimension nearly  
21 equal to the wafer radius as shown, or the full  
22 diameter.

23 Fig. 9B illustrates an embodiment that is particularly  
24 preferred, where the nozzle 120B, and thus the slot  
25 dimension, is less than the radius of the wafer 122B.  
26 In this embodiment the nozzle 120B must be moved, for  
27 example, in equal steps along the radial direction,

1 such that separate paste delivery tracks 140A, 140B,  
2 140C, etc. are defined. An exemplary mechanism for  
3 providing such movement is described below with respect  
4 to Fig. 9C. The combination of vacuum, paste pressure  
5 and dwell time of the nozzle over a via or collection  
6 of vias are important filling parameters. The  
7 embodiment shown in Fig. 9B allows wafer rotation speed  
8 to be adjusted for each separate paste delivery track  
9 to ensure that the average dwell time of the nozzle in  
10 any given location is approximately equal across the  
11 wafer. Another advantage of the smaller nozzle is that  
12 a higher overall paste pressure can be developed for a  
13 given amount of nozzle down force. The pressure of the  
14 paste multiplied by the area defined by the slot O-ring  
15 yields the force with which the nozzle must be held  
16 against the wafer surface to avoid any leakage under  
17 the O-ring seal. In general, any moving mechanical  
18 system such as that shown in Fig. 9B will have a  
19 maximum structural force at which it can properly  
20 operate. If the paste delivery area defined by the  
21 nozzle is reduced, the same mechanical down force will  
22 allow a higher nozzle pressure to be developed before  
23 the paste leakage condition is met.

24 Referring to Fig. 9C nozzle 120C is supported on an arm  
25 142 connected to a block 144 with a threaded hole 145.  
26 A worm gear drive assembly comprises a threaded shaft  
27 146, supported in fixed bearing blocks 148 and 150,  
28 extends through and engages the threads of hole 145.  
29 Shaft 146 is rotated by a motor 152 controlled by a

1 speed controller 154. Motion of block 144 resulting  
2 from rotation of shaft 146 causes nozzle 120C to move  
3 radially with respect to wafer 122C. It will be  
4 recognized that in addition to depositing separate  
5 paste delivery tracks 140A, 140B, 140C, etc., as  
6 described above with respect to Fig. 9B., it is  
7 possible, once paste delivery track 140A has been  
8 deposited, to continuously move nozzle 120C radially  
9 outward with respect to wafer 122C until a desired  
10 surface region has been covered with paste. Suitable  
11 continuous adjustment in the rotational speed of the  
12 wafer is made to assure reasonably uniform paste  
13 delivery, as described.

14 It is noted that the worm gear drive mechanism  
15 described above with reference to Fig. 9C is merely  
16 exemplary, and that any other suitable drive mechanism  
17 may be used. Further, any such drive mechanisms may be  
18 used in any embodiment of the invention described in  
19 the various figures, wherein translational motion is  
20 required.

21 The three general embodiments outlined describe only  
22 the paste application step itself. A production tool  
23 based on any of these preferably also comprise the  
24 following functions: automated wafer handling from/to a  
25 cassette to the paste apply stage (loadlock); provision  
26 for cleaning the edge (if necessary) of the wafer  
27 (similar to edge bead removal in a resist coater);  
28 automated paste pressure control, metering and

1 dispense; some form of automated inspection; and  
2 automated loading into a batch vacuum oven for low  
3 temperature drying *in-situ*.

4 The invention described herein has particular  
5 application to a semiconductor or glass substrate-based  
6 carrier for mounting and packaging multiple integrated  
7 circuit chips and/or other devices. The carrier is a  
8 freestanding chip or wafer with insulated, conductive  
9 through-vias exposed on its top and underside, to  
10 connect flip-chip and other device I/O through the  
11 carrier to next-level packaging, board, or other  
12 flip-chips mounted on the bottom side. However, it may  
13 be applied to any situation wherein a via, and in  
14 particular a deep via, must be filled with a viscous  
15 substance such as a paste.

16 Thus, it is noted that the foregoing has outlined some  
17 of the more pertinent objects and embodiments of the  
18 present invention. The concepts of this invention may  
19 be used for many applications. Thus, although the  
20 description is made for particular arrangements and  
21 methods, the intent and concept of the invention is  
22 suitable and applicable to other arrangements and  
23 applications. It will be clear to those skilled in the  
24 art that other modifications to the disclosed  
25 embodiments can be effected without departing from the  
26 spirit and scope of the invention. The described  
27 embodiments ought to be construed to be merely  
28 illustrative of some of the more prominent features and  
29 applications of the invention. Other beneficial results

1     can be realized by applying the disclosed invention in  
2     a different manner or modifying the invention in ways  
3     known to those familiar with the art. Thus, it should  
4     be understood that the embodiments has been provided as  
5     an example and not as a limitation. The scope of the  
6     invention is defined by the appended claims.